

# Nesting Monte Carlo for high-dimensional Non Linear PDEs

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# Outline

- 1 Introduction
- 2 Non linearity in  $u$
- 3 Non linearity in  $Du$
- 4 Towards full non linear equations

Resolution in high dimension (10-100) of

$$\begin{aligned}(-\partial_t u - \mathcal{L}u)(t, x) &= f(t, x, u(t, x), Du(t, x)), \\ u_T &= g,\end{aligned}\tag{1}$$

where

$$\mathcal{L}u(t, x) := \mu Du(t, x) + \frac{1}{2} \sigma \sigma^\top : D^2 u(t, x),\tag{2}$$

Parameters  $\mu$ ,  $\sigma$  may be time and space dependent.

# Recent bibliography

- Deterministic, dimension 3 or 4 for  $x$  : based on grids ,
- Classic BSDE with Monte Carlo [13], [9]: dimension till 6 or 7. Based on grids or basis functions for regressions;
- Recent Deep Learning techniques [6], [5] : numerical results in dimension over 100. No proof of convergence. Limitation not understood. Based on forward simulation of BSDE discretized with an Euler scheme.
- Branching techniques
  - for polynomial drivers [11] :dimension over 100, but restriction on maturity and non linearity size. Variance explodes rapidly,
  - General drivers [2], [1], no real restriction on maturity but grids needed : limited in dimension 4 or 5.
- In [8], [7], [12], algorithm based on Picard iterations, multi-level techniques and automatic differentiation

# Challenge

How to solve such equation in dimension over than 10 , 100 ?

- No grids,
- No basis functions

Use pure Monte carlo.

$$\begin{aligned}(-\partial_t u - \mathcal{L}u)(t, x) &= f(t, x, u(t, x)), \\ u_T &= g,\end{aligned}\tag{3}$$

where

$$\mathcal{L}u(t, x) := \mu Du(t, x) + \frac{1}{2} \sigma \sigma^\top : D^2 u(t, x),\tag{4}$$

so that  $\mathcal{L}$  is the generator associated to

$$\hat{X}_t = x + \mu t + \sigma dW_t,\tag{5}$$

# Idea of the algorithm : Time discretization of the SDE using Poisson process.

**Same as branching method:** i.i.d.  $(\tau_m)_{m \geq 1}$  density  $\rho$  exponential law with parameter  $\lambda$ , CDF :  $F = 1 - \bar{F}$ .

$$\begin{cases} T_0 & = 0, \\ T_{k+1} & = (T_k + \tau_k) \wedge T. \end{cases} \quad (6)$$

$(W_t^m)_{m \geq 1}$ , independent of  $(\tau_m)_{m \geq 1}$ .

- $W_t = W_t^1$  for  $t \in [0, T_1]$  ,
- $W_t := W_{T_k} + W_{t-T_k}^{k+1}$ , for all  $t \in [T_k, T_{k+1}]$ .
- $X_0 = x$
- $X_t = X_{T_k} + \mu(t - T_k) + \sigma W_{t-T_k}^{k+1}$   $t \in [T_k, T_{k+1}]$ ,  $\mathbb{P}$ -a.s.,

# Idea of the algorithm : Use Feynman Kac

Same as branching method:

$$\begin{aligned}u(0, x) &= \mathbb{E}_{0,x} \left[ g(X_T) + \int_0^T f(t, X_t, u(t, X_t)) dt \right] \\&= \mathbb{E}_{0,x} \left[ \bar{F}(T) \frac{g(X_T)}{\bar{F}(T)} + \int_0^T \frac{f(t, X_t, u(t, X_t))}{\rho(t)} \rho(t) dt \right] \\&= \mathbb{E}_{0,x} [\phi(0, T_1, X_{T_1}, u(T_1, X_{T_1}))],\end{aligned}$$

$$\phi(s, t, y, z) := \frac{\mathbf{1}_{\{t \geq T\}}}{\bar{F}(T-s)} g(y) + \frac{\mathbf{1}_{\{t < T\}}}{\rho(t-s)} f(t, y, z).$$



# Idea of the algorithm : Use nesting

Recursively noting  $u_n = u(T_n, X_{T_n})$  :

$$u_n = \mathbb{E}_{T_n, X_{T_n}} [\phi(T_n, T_{n+1}, X_{T_{n+1}}, u_{n+1})], \quad (7)$$

Truncated operator after  $p$  switches :

$$\begin{aligned} u_p^p &= g(X_{T_p}), \\ u_n^p &= \mathbb{E}_{T_n, X_{T_n}^n} [\phi(T_n, T_{n+1}, X_{T_{n+1}}, u_{n+1}^p)], \quad n < p, \quad \text{defined if } T_n < T \end{aligned} \quad (8)$$

# Assumption

- $f$  is uniformly Lipschitz in  $u$  with constant  $K$  :

$$|f(t, x, y) - f(t, x, w)| \leq K|y - w| \quad \forall t \in \mathbb{R}^+, x \in \mathbb{R}^d, (w, y) \in \mathbb{R}^2. \quad (9)$$

- $f$  is uniformly Lipschitz in  $x$ .

- Solution  $u \in C^{1,2}([0, T] \times \mathbb{R}^d)$

- $u$  is  $\theta$ -Hölder with  $\theta \in (0, 1]$  in time with constant  $\hat{K}$  :

$$|u(t, x) - u(\tilde{t}, x)| \leq \hat{K}|t - \tilde{t}|^\theta \quad \forall (t, \tilde{t}, x) \in [0, T] \times [0, T] \times \mathbb{R}^d,$$

- $u(t, x)$  has a quadratic growth in  $x$  uniformly in  $t$ ,

# Notations

- $(N_0, \dots, N_{p-1}) \in \mathbb{N}^p$ , **number of particles at each level**
- **Set of all particles till switch  $i$**  :  $Q_i = \{k = (k_1, \dots, k_i)\}$  for  $i \in \{1, \dots, p\}$  where  $k_j \in [1, N_{j-1}]$ .
- **Successors of  $k$**  :  
 $\tilde{Q}(k) = \{l = (k_1, \dots, k_i, m) / m \in \{1, \dots, N_i\}\} \subset Q_{i+1}$

## Switching dates

$$\begin{cases} T_{(j)} &= \tau_{(j)} \wedge T, j \in \{1, \dots, N_0\} \\ T_{\tilde{k}} &= (T_k + \tau_{\tilde{k}}) \wedge T, k = (k_1, \dots, k_i) \in Q_i, \tilde{k} \in \tilde{Q}(k) \end{cases} \quad (10)$$

## SDE

$$\begin{aligned} X_t^{(i)} &= X_0^\emptyset + \mu t + \sigma \bar{W}_t^{(i)}, \quad t \in [0, T_{(i)}], i = 1, N_0 \\ X_t^{\tilde{k}} &= X_{T_k}^k + \mu(t - T_k) + \sigma \bar{W}_{t-T_k}^{\tilde{k}}, \quad \text{for } \tilde{k} \in \tilde{Q}(k), \quad t \in [T_k, T_{\tilde{k}}], \quad \mathbb{P}\text{-a.s.}, \end{aligned} \quad (11)$$

$$\left\{ \begin{array}{l} \bar{u}_{\emptyset}^p = \frac{1}{N_0} \sum_{j=1}^{N_0} \phi(0, T_{(j)}, X_{T_{(j)}}^{(j)}, \bar{u}_{(j)}^p), \\ \bar{u}_k^p = \frac{1}{N_i} \sum_{\tilde{k} \in \tilde{Q}(k)} \phi(T_k, T_{\tilde{k}}, X_{T_{\tilde{k}}}^{\tilde{k}}, \bar{u}_{\tilde{k}}^p), \\ \quad \text{for } k = (k_1, \dots, k_i) \in Q_i, 1 < i < p, T_k < T, \\ \bar{u}_{\tilde{k}}^p = g(X_{T_{\tilde{k}}}^{\tilde{k}}) \quad \text{for } \tilde{k} \in Q_p. \end{array} \right.$$

## Proposition

*Under previous assumptions*

$$\mathbb{E}((\bar{u}_\emptyset^p - u(0, x))^2) \leq \prod_{i=1}^p \left(1 + \frac{8}{N_{i-1}}\right) \frac{K^{2p} e^{\lambda T}}{\lambda^p} T^{2\theta} \hat{K}^2 \frac{T^p}{p\Gamma(p)} + \sum_{i=0}^{p-1} \frac{K^{2i}}{N_i} \prod_{j=1}^i \left(1 + \frac{8}{N_{j-1}}\right) \frac{T^i e^{\lambda T}}{\lambda^i} \kappa_i \quad (12)$$

*with*

$$\kappa_i = \left( \frac{4T}{\lambda(i+1)!} \sup_{t \in [0, T]} \mathbb{E}(f(t, X_t, u(t, X_t))^2) + 2\mathbb{E}(g(X_T)^2) \left( \frac{1_{i>0}}{i\Gamma(i)} + 1_{i=0} \right) \right)$$

*and  $\Gamma(s) = \int_0^\infty t^{s-1} e^{-t} dt$  is the gamma function.*

# Numerical results for first non linear case $y^2$ dim 100

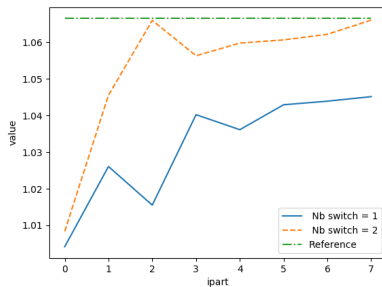
- $T = 1, T = 2,$
- $\mu = \frac{\mu_0}{d} \mathbf{1}_d, \sigma = \frac{\sigma_0}{\sqrt{d}} \mathbf{I}_d$  with  $\mu_0 = 0.2, \sigma_0 = 1.$
- $g(x) = \cos(\sum_{i=1}^d x_i)$
- 

$$f(t, x, u) = \cos\left(\sum_{i=1}^d x_i\right) \left(a + \frac{\sigma_0^2}{2}\right) e^{a(T-t)} + \sin\left(\sum_{i=1}^d x_i\right) \mu_0 e^{a(T-t)} - \\ r \cos\left(\sum_{i=1}^d x_i\right)^2 e^{2a(T-t)} + r \left(-e^{a(T-t)} \vee (u \wedge e^{a(T-t)})\right)^2$$

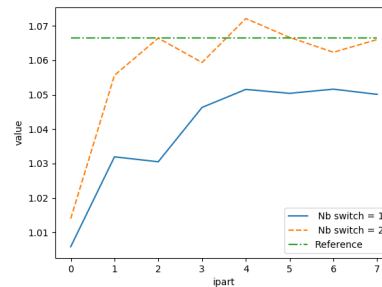
with  $a = 0.1, r = 0.1.$

- $u(t, x) = e^{a(T-t)} \cos(\sum_{i=1}^d x_i).$

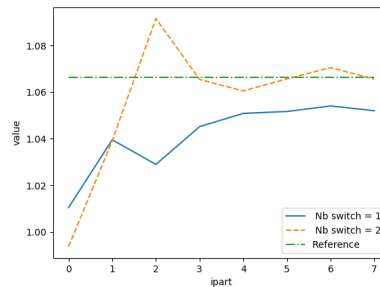
$$T = 1$$



$$\lambda = 0.2.$$



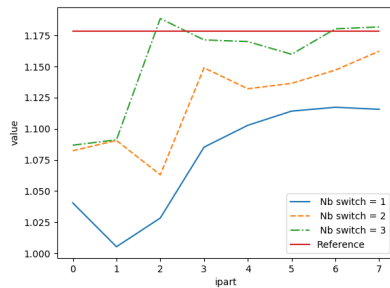
$$\lambda = 0.4.$$



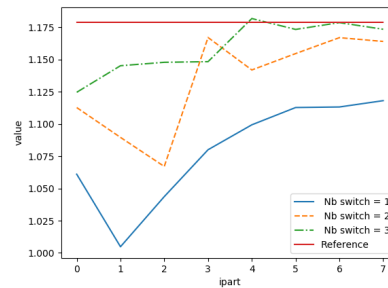
$$\lambda = 0.8.$$

Figure 1: Convergence for different number of switches for case 1,  $T = 1$ ,  $N_0 = 1000 \times 2^{\text{ipart}}$  and  $N_1 = 50 \times 2^{\text{ipart}}$

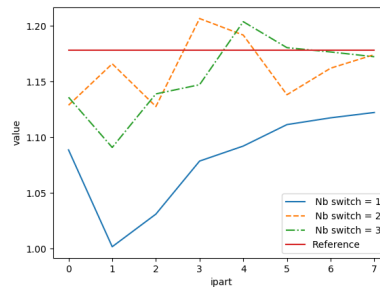
$$T = 2$$



$$\lambda = 0.2.$$



$$\lambda = 0.4.$$



$$\lambda = 0.8.$$

Figure 2: Convergence for different number of switches for case 1,  $T = 2$ ,  $N_0 = 1100 \times 2^{\text{ipart}}$ ,  $N_1 = 110 \times 2^{\text{ipart}}$ ,  $N_2 = 25 \times 2^{\text{ipart}}$



# CVA test case [10] Dim 6

- $\mu = -\frac{\sigma_0^2}{2} \mathbf{1}_d, \sigma = \sigma_0 \mathbf{I}_d,$

- 

$$f(t, x, u) = \beta(u^+ - u),$$

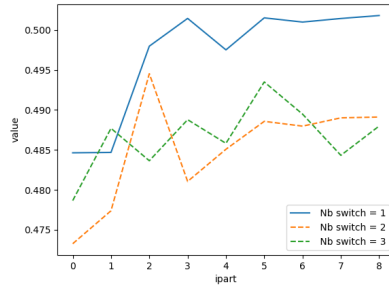
$$\beta = 0.03, \sigma_0 = 0.2.$$

- $X_0 = \mathbf{1}_d .$

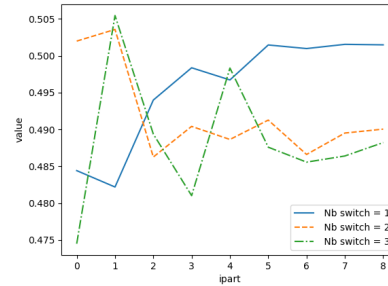
- $g(x) = \sum_{i=1}^d (1 - 2\mathbf{1}_{e^{x_i} > 1})$

- $T = 1.$

Reference deep learning primal and dual : lower bound 48.80, upper bound 48.83, value BS 47.73.



$\lambda = 0.1.$



$\lambda = 0.2.$

Figure 3: Convergence of the scheme on the CVA case.

- $\lambda = 0.1$  3 switches and  $ipart = 8$  we get 0.4880,
- $\lambda = 0.2$  we get 0.4882.

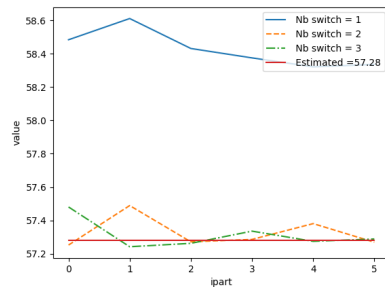
# BS default dim 100 risk [6]

- $\mu = (\mu_0 - \frac{\sigma_0^2}{2})\mathbf{1}_d, \sigma = \sigma_0\mathbf{1}_d.$
- $g(x) = \min_{i=1}^{100}(e^{x_i}),$
- 

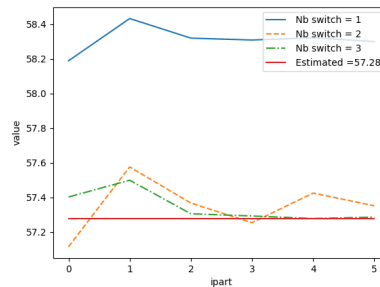
$$f(t, x, u) = - \left( (1 - \delta) \min\{\gamma^h, \max\{\gamma^l, \frac{\gamma^h - \gamma^l}{v^h - v^l}(u - v^h) + \gamma^h\}\} + R \right) u$$

- $T = 1, \delta = \frac{2}{3}, \mu_0 = 0.02, \sigma_0 = 0.2, v^h = 50, v^l = 70, \gamma^h = 0.2, \gamma^l = 0.02.$

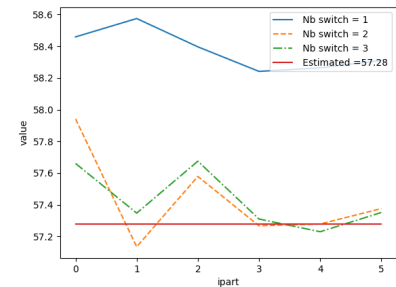
# Results Jentzen case



$\lambda = 0.2.$



$\lambda = 0.4.$



$\lambda = 0.8.$

Figure 4: Convergence of the scheme on the Black Scholes case with default  $N_0 = 36000 \times 2^{\text{ipart}}$ ,  $N_1 = 40 \times 2^{\text{ipart}}$ ,  $N_2 = 2^{\text{ipart}}$

A good accuracy 57.28 is achieved with two switches taking  $N_0 = 1152000$ ,  $N_1 = 4480$  in 26 seconds (224 cores) with  $\lambda = 0.2$ . Reference seems to be 57.30 according [6].

# Non linearity in $Du$

$$\begin{aligned}(-\partial_t u - \mathcal{L}u)(t, x) &= f(t, x, Du(t, x)), \\ u_T &= g, \quad t < T, \quad x \in \mathbb{R}^d,\end{aligned}\tag{13}$$

Assumptions:

- $\sigma$  non degenerated matrix,
- $f$  uniformly Lipschitz in  $x$  and in  $y$ :

$$|f(t, x, y) - f(t, x, w)| \leq K \|y - w\|_2, \quad \forall t \in [0, T], x \in \mathbb{R}^d, (w, y) \in \mathbb{R}^d \times \mathbb{R}^d.\tag{14}$$

- $u \in C^{1,2}([0, T] \times \mathbb{R}^d)$ ,
- $Du$  is  $\theta$ -Hölder in time with  $\theta \in (0, 1]$  :

$$\|Du(t, x) - Du(\tilde{t}, x)\| \leq \hat{K} |t - \tilde{t}|^\theta \quad \forall (t, \tilde{t}, x) \in [0, T] \times [0, T] \times \mathbb{R}^d,$$

- $u(t, x)$  and  $Du(t, x)$  have a quadratic growth in  $x$  uniformly in  $t$ .
- $g$  Lipschitz

$$|g(x) - g(y)| \leq \tilde{K} \|x - y\|_2 \quad \forall (x, y) \in \mathbb{R}^d \times \mathbb{R}^d.$$

# General idea

$(\tau_m)_{m \geq 1}$  with gamma distribution  $0 < u < 1$ ,  $\rho(x) = \lambda^u x^{u-1} \frac{e^{-\lambda x}}{\Gamma(u)}$ . Same as before

$$\begin{aligned} u(0, x) &= \mathbb{E}_{0,x} \left[ \overline{F}(T) \frac{g(W_T)}{\overline{F}(T)} + \int_0^T \frac{f(t, X_t, Du(t, X_t))}{\rho(t)} \rho(t) dt \right] \\ &= \mathbb{E}_{0,x} [\hat{\phi}(0, T_1, X_{T_1}, Du(T_1, X_{T_1}))], \end{aligned} \quad (15)$$

with  $\hat{\phi}(s, t, x, z) := \frac{\mathbf{1}_{\{t \geq T\}}}{\overline{F}(T-s)} g(x) + \frac{\mathbf{1}_{\{t < T\}}}{\rho(t-s)} f(t, x, z)$ .

Define  $Du(T_1, X_{T_1})$  using the automatic differentiation rule :

$$Du(T_1, X_{T_1}) = \mathbb{E}_{T_1, X_{T_1}} \left[ \sigma^{-\top} \frac{W_{T_2} - W_{T_1}}{T_2 - T_1} \phi(T_1, T_2, X_{T_1}, X_{T_2}, Du(T_2, X_{T_2})) \right], \quad (16)$$

with  $\phi(s, t, x, y, z) := \frac{\mathbf{1}_{\{t \geq T\}}}{\overline{F}(T-s)} (g(y) - g(x)) + \frac{\mathbf{1}_{\{t < T\}}}{\rho(t-s)} f(t, y, z)$ .

# A first estimator

$$\left\{ \begin{array}{l} \bar{u}_\emptyset^p = \frac{1}{N_0} \sum_{j=1}^{N_0} \hat{\phi}(\mathbf{0}, T_{(j)}, X_{T_{(j)}}^{(j)}, D\bar{u}_{(j)}^p), \\ D\bar{u}_k^p = \frac{1}{N_i} \sum_{\tilde{k} \in \tilde{Q}(k)} \phi(T_k, T_{\tilde{k}}, X_{T_k}^k, X_{T_{\tilde{k}}}^{\tilde{k}}, D\bar{u}_{\tilde{k}}^p) \sigma^{-\top} \frac{\bar{W}_{T_{\tilde{k}} - T_k}^{\tilde{k}}}{T_{\tilde{k}} - T_k} \\ \quad \text{for } k = (k_1, k_2, \dots, k_i) \in Q_i, i < p, \\ D\bar{u}_{\tilde{k}}^p = Dg(X_{T_{\tilde{k}}}^{\tilde{k}}) \quad \text{for } \tilde{k} \in Q_p \end{array} \right.$$

## Proposition

*Under previous assumptions*

$$\begin{aligned}
 \mathbb{E}\left((\bar{u}_\emptyset^p - u(0, x))^2\right) &\leq \prod_{i=1}^p \left(1 + \frac{8}{N_{i-1}}\right) \frac{\Gamma(u)^p e^{\lambda T}}{\lambda^p} \frac{T^{(1-u)p+1+2\theta}}{(1-u)^{p-1}(2-u)} C(\sigma)^{p-1} \hat{K}^2 K^{2p} + \\
 &4 \sum_{i=0}^{p-1} \frac{K^{2i}}{N_i} \prod_{j=1}^i \left(1 + \frac{8}{N_{j-1}}\right) \frac{\Gamma(u)^{i+1} e^{\lambda T}}{\lambda^{i+1}} \frac{T^{(1-u)(i+1)+1}}{(1-u)^i(2-u)} \bar{C}(\sigma)^i \hat{F} + \\
 &2 \sum_{i=1}^{p-1} \frac{K^{2i}}{N_i} \prod_{j=1}^i \left(1 + \frac{8}{N_{j-1}}\right) \frac{\Gamma(u)^{i+1} e^{\lambda T}}{\lambda^i} \frac{T^{(1-u)i+1}}{(1-u)^{i-1}(2-u)} \frac{\bar{C}(\mu, \sigma, T) C(\sigma)^{i-1} \tilde{K}^2}{\Gamma(u) - \gamma(u, \lambda T)} + \\
 &\frac{2}{N_0} \frac{\Gamma(u)}{\Gamma(u) - \gamma(u, \lambda T)} \mathbb{E}(g(X_T)^2)
 \end{aligned}$$

where

$$\hat{F} = \sup_{t \in [0, T]} \mathbb{E}[f(t, X_t, Du(t, X_t))^4]^{\frac{1}{2}},$$



# Original particle and “antithetic” by example : $d = 1$ , $\mu = 0$ , $\sigma = 1$ , the brownian case.

Let us consider the original particle  $k = (k_1, k_2, k_3)$  such that  $T_{(k_1, k_2, k_3)} = T$

$$\begin{aligned}
 X_{T(k_1)}^{(k_1)} &= \bar{W}_{T(k_1)}^{(k_1)}, & X_{T(k_1)}^{(k_1^{(-)})} &= -\bar{W}_{T(k_1)}^{(k_1)} \\
 X_T^{(k_1, k_2, k_3)} &= \bar{W}_{T(k_1)}^{(k_1)} + \bar{W}_{T(k_1, k_2) - T(k_1)}^{(k_1, k_2)} + \bar{W}_{T - T(k_1, k_2)}^{(k_1, k_2, k_3)} \\
 X_T^{(k_1^-, k_2, k_3)} &= -\bar{W}_{T(k_1)}^{(k_1)} + \bar{W}_{T(k_1, k_2) - T(k_1)}^{(k_1, k_2)} + \bar{W}_{T - T(k_1, k_2)}^{(k_1, k_2, k_3)} \\
 X_T^{(k_1, k_2^-, k_3)} &= \bar{W}_{T(k_1)}^{(k_1)} - \bar{W}_{T(k_1, k_2) - T(k_1)}^{(k_1, k_2)} + \bar{W}_{T - T(k_1, k_2)}^{(k_1, k_2, k_3)} \\
 X_T^{(k_1, k_2^-, k_3^-)} &= \bar{W}_{T(k_1)}^{(k_1)} - \bar{W}_{T(k_1, k_2) - T(k_1)}^{(k_1, k_2)} - \bar{W}_{T - T(k_1, k_2)}^{(k_1, k_2, k_3)} \\
 &\dots
 \end{aligned}$$

- for  $f$  regular  $f(X_T^{(k_1, k_2, k_3)}) - f(X_T^{(k_1^-, k_2, k_3)}) = O(\sqrt{T(k_1)})$
- Notation antithetic  $(k_1, k_2)^- = (k_1, k_2^-)$ ,  $(k_1^-, k_2)^- = (k_1^-, k_2^-)$ ,
- Notation original particle  $o((k_1, k_2^-, k_3^-)) = (k_1, k_2, k_3)$ .

# A second framework : general notations

- $Q_1^o = \{(k_1), (k_1^-)\}$  where  $k_1 \in \{1, \dots, N_1\}$ ,
- To a particle  $(k_1) \in Q_1$  associate an antithetic particle noted  $k_1^-$ .
- The set  $Q_i^o$  defined by recurrence :

$$Q_{i+1}^o = \{(k_1, \dots, k_i, k_{i+1}) / (k_1, \dots, k_i) \in Q_i^o, k_{i+1} \in \{1, \dots, N_{i+1}, 1^-, \dots, N_{i+1}^-\}\}$$

- $k = (k_1, \dots, k_i) \in Q_i^o$  its original particle  $o(k) = (\hat{k}_1, \dots, \hat{k}_i)$  where  $\hat{k}_j = l$  if  $k_j = l$  or  $l^-$
- when  $k = (k_1, \dots, k_i)$  is such that  $k_i \in \mathbb{N}$ ,  $k^- := (k_1, \dots, k_{i-1}, k_i^-)$ .
- By convention  $T_k = T_{o(k)}$ ,  $\tau_k = \tau_{o(k)}$  and  $\bar{W}_t^k = \bar{W}_t^{o(k)}$ . For  $k = (k_1, \dots, k_i) \in Q_i^o$  we introduce the set
  - $\tilde{Q}^o(k) = \{l = (k_1, \dots, k_i, m) / m \in \{1, \dots, N_i\}\} \subset Q_{i+1}^o$
  - and  $\hat{Q}^o(k) = \{l = (k_1, \dots, k_i, m) / m \in \{1, \dots, N_i, 1^-, \dots, N_i^-\}\} \subset Q_{i+1}^o$

$k = (k_1, \dots, k_i) \in Q_i^o$  and  $\tilde{k} = (k_1, \dots, k_i, k_{i+1}) \in \hat{Q}^o(k)$  we define the following trajectories :

$$W_s^{\tilde{k}} := W_{T_k}^k + \mathbf{1}_{k_{i+1} \in \mathbb{N}} \bar{W}_{s-T_k}^{o(\tilde{k})} - \mathbf{1}_{k_{i+1} \notin \mathbb{N}} \bar{W}_{s-T_k}^{o(\tilde{k})}, \quad \text{and} \quad (17)$$

$$X_s^{\tilde{k}} := x + \mu s + \sigma W_s^{\tilde{k}}, \quad \forall s \in [T_k, T_{\tilde{k}}]. \quad (18)$$

# Add some assumptions

- $Du$  is uniformly Lipschitz in  $x$  such that for  $\bar{K} > 0$ :

$$\|Du(t, x) - Du(t, y)\|_2 \leq \bar{K} \|x - y\|_2 \quad \forall (t, x, y) \in [0, T] \times \mathbb{R}^d \times \mathbb{R}^d.$$

- $f$  is uniformly Lipschitz in  $x$  :

$$|f(t, x, z) - f(t, y, z)| \leq \underline{K} \|x - y\|_2, \quad \forall (t, x, y, z) \in [0, T] \times \mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d$$

$$\left\{ \begin{array}{l} \bar{u}_0^p = \frac{1}{N_0} \sum_{j=1}^{N_0} \frac{(\hat{\phi}(0, T_{(j)}, X_{T_{(j)}}^{(j)}, D\bar{u}_{(j)}^p) + \hat{\phi}(0, T_{(j)}, X_{T_{(j)}}^{(j)-}, D\bar{u}_{(j)-}^p))}{2}, \\ D\bar{u}_k^p = \frac{1}{N_i} \sum_{\tilde{k} \in \tilde{Q}^o(k)} \tilde{W}^{\tilde{k}} \frac{1}{2} (\hat{\phi}(T_k, T_{\tilde{k}}, X_{T_{\tilde{k}}}^{\tilde{k}}, D\bar{u}_{\tilde{k}}^p) - \hat{\phi}(T_k, T_{\tilde{k}}, X_{T_{\tilde{k}}}^{\tilde{k}-}, D\bar{u}_{\tilde{k}-}^p)), \\ \text{for } k = (k_1, \dots, k_i) \in Q_i^o, i < p, \\ D\bar{u}_{\tilde{k}}^p = Dg(X_{T_{\tilde{k}}}^{\tilde{k}}) \text{ for } \tilde{k} \in Q_p^o \end{array} \right.$$

where

- $\hat{\phi}(s, t, x, z) := \frac{\mathbf{1}_{\{t \geq T\}}}{F(T-s)} g(x) + \frac{\mathbf{1}_{\{t < T\}}}{\rho(t-s)} f(t, x, z).$
- $\tilde{W}^{\tilde{k}} = \sigma^{-\top} \frac{\bar{W}_{T_{\tilde{k}} - T_k}^{o(\tilde{k})}}{T_{\tilde{k}} - T_k}.$

## Proposition

*Under previous assumptions:*

$$\begin{aligned}
 \mathbb{E}\left((\bar{u}_0^p - u(0, x))^2\right) &\leq \prod_{i=1}^p \left(1 + \frac{8}{N_{i-1}}\right) \frac{\Gamma(u)^p e^{\lambda T}}{\lambda^p} \frac{T^{(1-u)p+1+2\theta}}{(1-u)^{p-1}(2-u)} C(\sigma)^{p-1} \hat{K}^2 K^{2p} + \\
 &\sum_{i=1}^{p-1} \frac{K^{2i}}{N_i} \prod_{j=1}^i \left(1 + \frac{8}{N_{j-1}}\right) \bar{C}(\sigma, K, \bar{K}, \underline{K}) C(\sigma)^{i-1} \frac{\Gamma(u)^{i+1} e^{\lambda T}}{\lambda^{i+1}} \frac{T^{(1-u)i+3-u}}{(2-u)^2(1-u)^{i-1}} + \\
 &\sum_{i=1}^{p-1} \frac{K^{2i}}{2N_i} \prod_{j=1}^i \left(1 + \frac{8}{N_{j-1}}\right) C(\sigma)^{i-1} \frac{\tilde{K}^2 \Gamma(u)^{i+1} e^{\lambda T}}{\lambda^i (\Gamma(u) - \gamma(u, \lambda T))} \bar{C}(\sigma) \frac{T^{(1-u)i+1}}{(2-u)(1-u)^{i-1}} + \\
 &\frac{4}{N_0} \frac{\Gamma(u)}{\lambda} e^{\lambda T} \frac{T^{2-u}}{2-u} \hat{F} + \frac{2}{N_0} \frac{\Gamma(u)}{\Gamma(u) - \gamma(u, \lambda T)} \mathbb{E}(g(X_T)^2) \quad (19)
 \end{aligned}$$

Using two switches, the use of an exponential law is possible.

# Numerical results on a Burgers case [5], [3]

- $\mu = 0, \sigma = d\mathbf{I}_d, T = 1,$



$$f(t, x, y, z) = \left(y - \frac{2+d}{2d}\right) \left(d \sum_{i=1}^d z_i\right),$$



$$g(x) = \frac{e^{T + \frac{1}{d} \sum_{i=1}^d x_i}}{1 + e^{T + \frac{1}{d} \sum_{i=1}^d x_i}}.$$

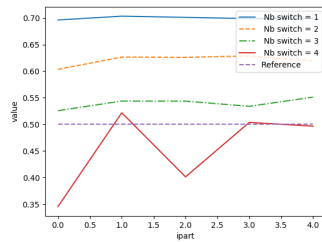
The explicit solution given by [5] is

$$u(t, x) = \frac{e^{t + \frac{1}{d} \sum_{i=1}^d x_i}}{1 + e^{t + \frac{1}{d} \sum_{i=1}^d x_i}}.$$

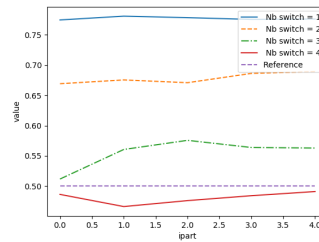
Solution estimated by the two estimators by

$$N_i^{ipart} = N_i^0 \times 2^{ipart}.$$

# Bürgers, estimator 1 , reference 0.5, $(N_0^0, N_1^0, N_2^0, N_3^0) = (1000, 40, 40, 30)$

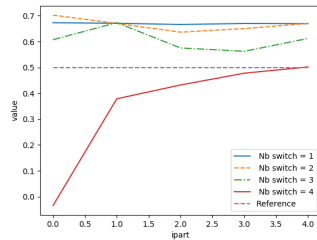


$\lambda = 0.1.$

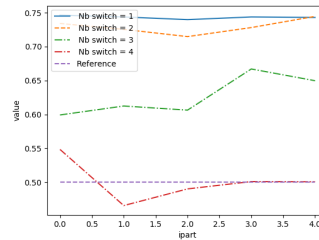


$\lambda = 0.2.$

Bürgers case: convergence in dimension 10 using a gamma law with  $u = 0.8$



$\lambda = 0.1$



$\lambda = 0.2$

Bürgers case: convergence with estimator 1 in dimension 20 using a gamma law with  $u = 0.8$ .

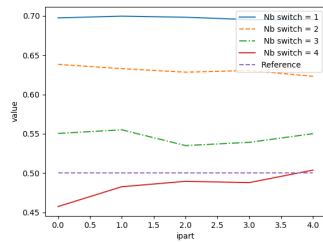


# Bürgers estimator 1, time for 224 cores

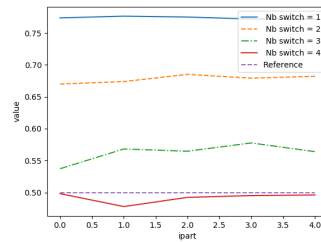
In dimension 10 and 20, we obtain very good results with 4 switches and  $ipart = 4$ ,

- getting in dimension 10 a value 0.496 for  $\lambda = 0.1$  in 80 seconds and 0.4910 for  $\lambda = 0.2$  in 1000 seconds,
- getting in dimension 20 a value 0.501 for  $\lambda = 0.1$  in 350 seconds and 0.5006 for  $\lambda = 0.2$  in 1400 seconds.

Bürgers : estimator 2, reference 0.5, gamma law,  
 $(N_0^0, N_1^0, N_2^0, N_3^0) = (1000, 40, 40, 30)$

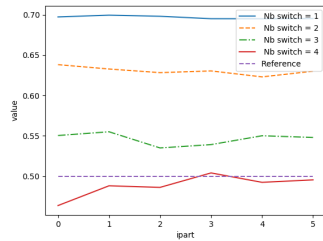


$\lambda = 0.1.$

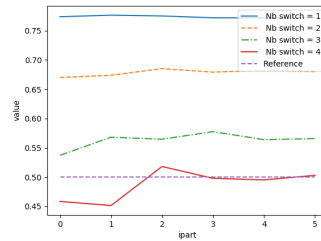


$\lambda = 0.2.$

Bürgers case: convergence with estimator 2 in dimension 10 using a gamma law with  $u = 0.9$ .



$\lambda = 0.1.$

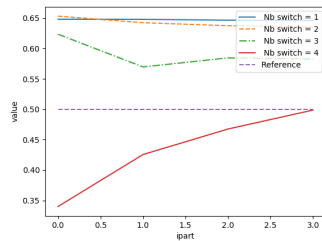


$\lambda = 0.2.$

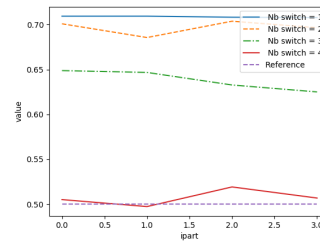
Bürgers case: convergence with estimator 2 in dimension 20 with a gamma law with  $u = 0.9$ .

# Estimator 2 and exponential law,

$(N_0^0, N_1^0, N_2^0, N_3^0) = (1000, 40, 40, 4)$ , time for 224 cores



$\lambda = 0.1.$



$\lambda = 0.2.$

Bürgers case: convergence with estimator 2 in dimension 20 with an exponential law, time for 224 cores

With 4 switches,  $ipart = 3$  we get very good results :

- Solution 0.499, computational time 14 seconds with  $\lambda = 0.1$ ,
- Solution 0.506 , computational time 55 seconds with  $\lambda = 0.2$ .

The variance using exponential laws seems to be lower and generation of an exponential law takes far less time than with general gamma laws.

# A HJB case in dimension 100 [5],[6], [4]



$$\mu = 0, \quad \sigma = \sqrt{2}\mathbf{I}_d, \quad T = 1,$$
$$f(t, x, z) = -\theta \|z\|_2^2,$$



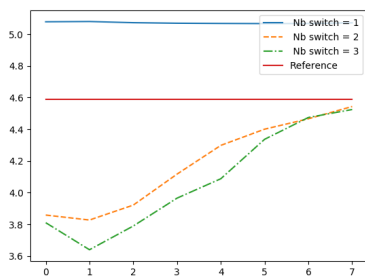
$$u(t, x) = -\frac{1}{\theta} \log (\mathbb{E}[e^{-\theta g(x + \sqrt{2}W_{T-t})}]). \quad (20)$$



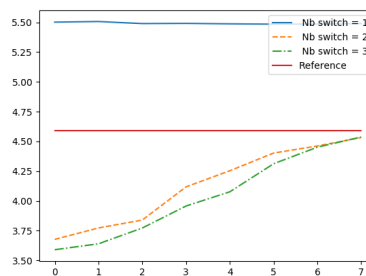
$$g(x) = \log\left(\frac{1 + \|x\|_2^2}{2}\right),$$

- solution searched for  $t = 0$ ,  $x = 0\mathbf{1}_d$ .
- References 4.59 with  $\theta = 1$ , 4.49 with  $\theta = 10$ , and 4.36 with  $\theta = 20$

# Results with estimator 1 $(N_0^0, N_1^0, N_2^0) = (1000, 20, 20)$



$\lambda = 0.1$

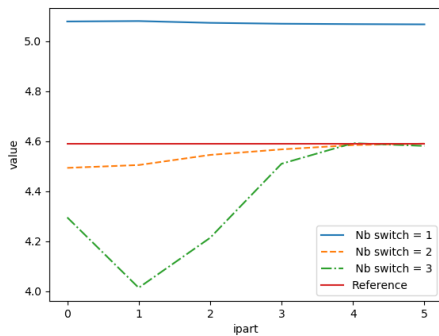


$\lambda = 0.2$

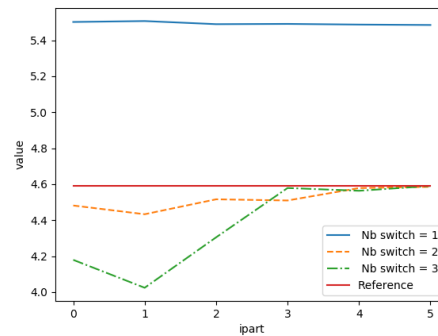
HJB convergence case for  $\theta = 1$  and estimator 1 using a gamma law with  $u = 0.8$ .

Very slow convergence with this non linearity. Estimator 1 too costly for  $\theta = 10, \theta = 20$ .

Estimator 2 , gamma law ,  $\theta = 1$ ,  
 $(N_0^0, N_1^0, N_2^0) = (1000, 10, 1)$



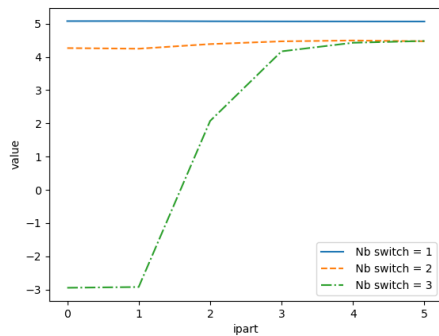
$\lambda = 0.1$



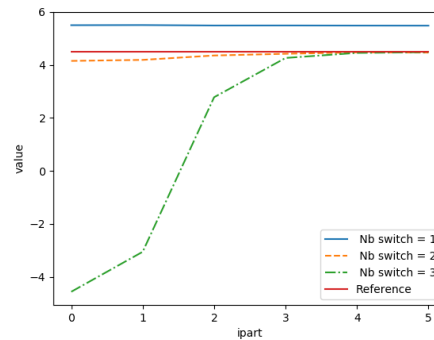
$\lambda = 0.2$

Figure 5: HJB convergence case for  $\theta = 1$  and estimator 2 using a gamma law with  $u = 0.9$ .

Estimator 2 , gamma law ,  $\theta = 10$ ,  
 $(N_0^0, N_1^0, N_2^0) = (1000, 10, 5)$



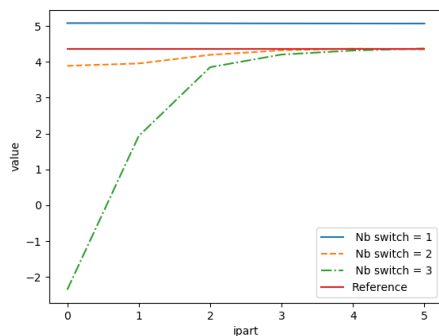
$\lambda = 0.1$



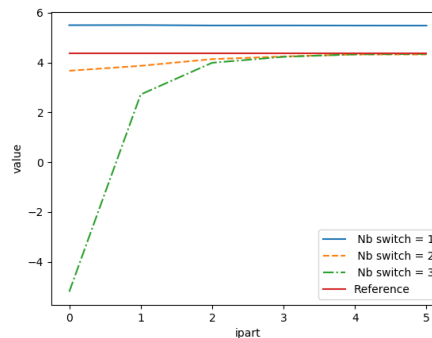
$\lambda = 0.2$

Figure 6: HJB convergence case for  $\theta = 10$  and estimator 2 using a gamma law with  $u = 0.9$ .

Estimator 2 , gamma law ,  $\theta = 20$ ,  
 $(N_0^0, N_1^0, N_2^0) = (1000, 40, 20)$



$\lambda = 0.1$

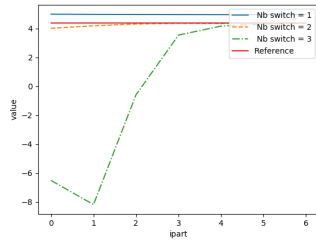


$\lambda = 0.2$

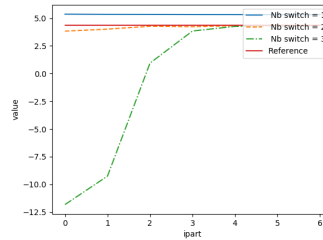
Figure 7: HJB convergence case for  $\theta = 20$  and estimator 2 using a gamma law with  $u = 0.9$ .



# Estimator 2 , exponential law, $\theta = 20$ , $(N_0^0, N_1^0, N_2^0) = (1000, 40, 10)$



$\lambda = 0.1$



$\lambda = 0.2$

HJB convergence case for  $\theta = 20$  and estimator 2 using an exponential law.

Solution in 10 seconds,  $\lambda = 0.1$ , 2 switches, precision less than 0.5% using  $(N_0, N_1) = (8000, 320)$ .

Very accurate solution, precision 0.1% with both  $\lambda$  necessary to use 3 switches with

$(N_0, N_1, N_2) = (64000, 2560, 640)$  and computational time explodes to 30000 seconds with  $\lambda = 0.1$  and 80000 seconds with  $\lambda = 0.2$ .

# The general problem Full Non Linear problem

$$\begin{aligned}(-\partial_t u - \mathcal{L}u)(t, x) &= f(t, x, u(t, x), Du(t, x), D^2u(t, x)), \\ u(T, x) &= g(x), \quad t < T, \quad x \in \mathbb{R}^d,\end{aligned}\tag{21}$$

- $\mu \in \mathbb{R}^d$ , and  $\sigma \in \mathbb{M}^d$  is some constant matrix.
- 

$$\rho(x) = \lambda^\alpha x^{\alpha-1} \frac{e^{-\lambda x}}{\Gamma(\alpha)}, \quad 1 \geq \alpha > 0.\tag{22}$$



$$Q_1^o = Q_1$$

$$Q_{i+1}^o = \{(k_1, \dots, k_i, k_{i+1}) / (k_1, \dots, k_i) \in Q_i^o, k_{i+1} \in \{1, \dots, N_{i+1}, 1_1, \dots, (N_{i+1})_1\}\}$$

- For  $k = (k_1, \dots, k_i) \in Q_i^o$  its original particle  $o(k) \in Q_i$  such that  $o(k) = (\hat{k}_1, \dots, \hat{k}_i)$  where  $\hat{k}_j = l$  if  $k_j = l, l_1$  or  $l_2$ .
- For  $k = (k_1, \dots, k_i) \in Q_i^o$  set of its non fictitious sons

$$\tilde{Q}(k) = \{l = (k_1, \dots, k_i, m) / m \in \{1, \dots, N_i\}\} \subset Q_{i+1}^o,$$



$$\kappa(k) = 0 \text{ for } k_i \in \mathbb{N},$$

$$\kappa(k) = 1 \text{ for } k_i = l_1, l \in \mathbb{N}$$

$$\kappa(k) = 2 \text{ for } k_i = l_2, l \in \mathbb{N}$$

# Switching dates and trajectories

$$\begin{cases} T_{(j)} &= \tau_{(j)} \wedge T, j \in \{1, \dots, N_0\} \\ T_{\tilde{k}} &= (T_k + \tau_{\tilde{k}}) \wedge T, k = (k_1, \dots, k_i) \in Q_i, \tilde{k} \in \tilde{Q}(k) \end{cases} \quad (23)$$

$$W_s^{\tilde{k}} := W_{T_k}^k + \mathbf{1}_{\kappa(\tilde{k})=0} \bar{W}_{s-T_k}^{o(\tilde{k})} - \mathbf{1}_{\kappa(\tilde{k})=1} \bar{W}_{s-T_k}^{o(\tilde{k})}, \quad \text{and} \quad (24)$$

$$X_s^{\tilde{k}} := x + \mu s + \sigma W_s^{\tilde{k}}, \quad \forall s \in [T_k, T_{\tilde{k}}], \quad (25)$$

Example:  $d = 1, \mu = 0, \sigma = 1$

Let us consider the original particle  $k = (1, 1, 1)$  such that  $T_{(1,1,1)} = T$

$$X_T^{(1,1,1)} = \bar{W}_{T(1)}^{(1)} + \bar{W}_{T(1,1)-T(1)}^{(1,1)} + \bar{W}_{T-T(1,1)}^{(1,1,1)}$$

$$X_T^{(1_1,1,1)} = -\bar{W}_{T(1)}^{(1)} + \bar{W}_{T(1,1)-T(1)}^{(1,1)} + \bar{W}_{T-T(1,1)}^{(1,1,1)}$$

$$X_T^{(1,1_1,1)} = \bar{W}_{T(1)}^{(1)} - \bar{W}_{T(1,1)-T(1)}^{(1,1)} + \bar{W}_{T-T(1,1)}^{(1,1,1)}$$

$$X_T^{(1_2,1_1,1)} = -\bar{W}_{T(1,1)-T(1)}^{(1,1)} + \bar{W}_{T-T(1,1)}^{(1,1,1)}$$

...

- For  $f$  regular,  $f(X_T^{(1,1,1)}) + f(X_T^{(1_1,1,1)}) - 2f(X_T^{(1_2,1,1)}) = O(T_{(1)})$ .
- Notation  $(1, 1, 1)^1 = (1, 1, 1_1)$ ,  $(1, 1, 1)^2 = (1, 1, 1_2)$ .

# Weights and $\phi$ function

$$\phi(s, t, x, y, z, \theta) := \frac{\mathbf{1}_{\{t \geq T\}}}{\bar{F}(T - s)} g(x) + \frac{\mathbf{1}_{\{t < T\}}}{\rho(t - s)} f(t, x, y, z, \theta), \quad (26)$$

and gradient weight:

$$\mathbb{V}^k = \sigma^{-\top} \frac{\bar{W}_{T_k - T_{k-}}^k}{T_k - T_{k-}},$$

second order derivative weight:

$$\mathbb{W}^k = (\sigma^\top)^{-1} \frac{\bar{W}_{T_k - T_{k-}}^k (\bar{W}_{T_k - T_{k-}}^k)^\top - (T_k - T_{k-}) I_d}{(T_k - T_{k-})^2} \sigma^{-1}. \quad (27)$$

# The scheme

$$\left\{ \begin{array}{l}
 \bar{u}_\emptyset^p = \frac{1}{N_0} \sum_{j=1}^{N_0} \phi \left( 0, T_{(j)}, X_{T_{(j)}}^{(j)}, \bar{u}_{(j)}^p, D\bar{u}_{(j)}^p, D^2\bar{u}_{(j)}^p \right), \\
 \bar{u}_k^p = \frac{1}{N_i} \sum_{\tilde{k} \in \tilde{Q}(k)} \frac{1}{2} \left( \phi \left( T_k, T_{\tilde{k}}, X_{T_{\tilde{k}}}^{\tilde{k}}, \bar{u}_{\tilde{k}}^p, D\bar{u}_{\tilde{k}}^p, D^2\bar{u}_{\tilde{k}}^p \right) + \right. \\
 \quad \left. \phi \left( T_k, T_{\tilde{k}}, X_{T_{\tilde{k}}}^{\tilde{k}1}, \bar{u}_{\tilde{k}1}^p, D\bar{u}_{\tilde{k}1}^p, D^2\bar{u}_{\tilde{k}1}^p \right) \right), \quad \text{for } k = (k_1, \dots, k_i) \in Q_i^o, 0 < i < p, \\
 D\bar{u}_k^p = \frac{1}{N_i} \sum_{\tilde{k} \in \tilde{Q}(k)} \mathbb{V}^{\tilde{k}} \frac{1}{2} \left( \phi \left( T_k, T_{\tilde{k}}, X_{T_{\tilde{k}}}^{\tilde{k}}, \bar{u}_{\tilde{k}}^p, D\bar{u}_{\tilde{k}}^p, D^2\bar{u}_{\tilde{k}}^p \right) - \right. \\
 \quad \left. \phi \left( T_k, T_{\tilde{k}}, X_{T_{\tilde{k}}}^{\tilde{k}1}, \bar{u}_{\tilde{k}1}^p, D\bar{u}_{\tilde{k}1}^p, D^2\bar{u}_{\tilde{k}1}^p \right) \right), \quad \text{for } k = (k_1, \dots, k_i) \in Q_i^o, 0 < i < p, \\
 D^2\bar{u}_k^p = \frac{1}{N_i} \sum_{\tilde{k} \in \tilde{Q}(k)} \mathbb{W}^{\tilde{k}} \frac{1}{2} \left( \phi \left( T_k, T_{\tilde{k}}, X_{T_{\tilde{k}}}^{\tilde{k}}, \bar{u}_{\tilde{k}}^p, D\bar{u}_{\tilde{k}}^p, D^2\bar{u}_{\tilde{k}}^p \right) + \right. \\
 \quad \left. \phi \left( T_k, T_{\tilde{k}}, X_{T_{\tilde{k}}}^{\tilde{k}1}, \bar{u}_{\tilde{k}1}^p, D\bar{u}_{\tilde{k}1}^p, D^2\bar{u}_{\tilde{k}1}^p \right) - \right. \\
 \quad \left. 2\phi \left( T_k, T_{\tilde{k}}, X_{T_{\tilde{k}}}^{\tilde{k}2}, \bar{u}_{\tilde{k}2}^p, D\bar{u}_{\tilde{k}2}^p, D^2\bar{u}_{\tilde{k}2}^p \right) \right), \quad \text{for } k = (k_1, \dots, k_i) \in Q_i^o, 0 < i < p, \\
 \bar{u}_k^p = g(X_{T_k}^k), D\bar{u}_k^p = Dg(X_{T_k}^k), D^2\bar{u}_k^p = D^2g(X_{T_k}^k), \quad \text{for } k \in Q_p^o,
 \end{array} \right. \quad (28)$$

$$f(\theta) = A : \theta$$

## Assumption

Equation (21) has a solution  $u$  such that

- $u \in C^{1,2p}([0, T] \times \mathbb{R}^d)$  with uniformly bounded derivatives in  $x$  and  $t$ .
- $D^{2i}u$  is  $\theta$ -Hölder with  $\theta \in (0, 1]$  in time with constant  $\hat{K}$  for  $i = 1$  to  $p$ :

$$|D^{2p}u(t, \cdot) - D^{2p}u(\tilde{t}, \cdot)|_{\infty} \leq \hat{K}|t - \tilde{t}|^{\theta} \quad \forall (t, \tilde{t}) \in [0, T] \times [0, T]. \quad (29)$$



## Proposition

*There exists some functions of  $u$ :  $C_1(u)$ ,  $C_2(u)$ ,  $C_3(u)$ , and two functions  $\hat{C}(T)$  and  $C(\sigma)$  such that we have the following error given by the estimator (28):*

$$\begin{aligned} \mathbb{E}((\bar{u}_\emptyset^p - u(0, x))^2) &\leq C_1(u) \hat{C}(T)^{2p} C(\sigma)^{p-1} \|A\|_2^{2p} T^{2\theta} \frac{\gamma(\alpha, \lambda T p)}{\Gamma(\alpha)} + \\ &\sum_{i=0}^{p-1} \frac{C_2(u)}{N_i} \hat{C}(T)^{2i+2} C(\sigma)^i \|A\|_2^{2i+2} \frac{\gamma(\alpha, \lambda T(i+1))}{\Gamma(\alpha)} + \\ &\sum_{i=0}^{p-1} \frac{C_3(u)}{N_i} \frac{\hat{C}(T)^{2i}}{\bar{F}(T)^2} C(\sigma)^i \frac{\gamma(\alpha, \lambda T i)}{\Gamma(\alpha)} \end{aligned}$$

# Semi Linear degenerated, $\sigma$ not invertible

$$(-\partial_t u - \mathcal{L}u)(t, x) = f(t, x, u(t, x), Du(t, x)),$$

$$\hat{\mathcal{L}}u(t, x) := \mu Du(t, x) + \frac{1}{2} \hat{\sigma} \hat{\sigma}^\top : D^2 u(t, x)$$

with  $\hat{\sigma}$  invertible.

$$\begin{aligned} (-\partial_t u - \hat{\mathcal{L}}u)(t, x) &= \tilde{f}(t, x, u(t, x), Du(t, x), D^2 u(t, x)) \\ \tilde{f}(t, x, u(t, x), Du(t, x), D^2 u(t, x)) &:= f(t, x, u(t, x), Du(t, x)) - \\ &\quad \frac{1}{2} (\hat{\sigma} \hat{\sigma}^\top - \sigma \sigma^\top) : D^2 u(t, x) \end{aligned}$$

# Semi linear degenerated case



$$\mathcal{L}u(t, x) := k(m - x)Du(t, x) + \frac{1}{2}\bar{\sigma}(x)^2 : D^2u(t, x),$$

and  $k = \hat{k}I_d$ ,  $\hat{k} \in \mathbb{R}^+$ ,  $m = \hat{m}\mathbf{1}_d$ ,  $\hat{m} \in \mathbb{R}^+$ ,  $\bar{\sigma}(x)$  diagonal  
 $\bar{\sigma}_{i,i}(x) = \hat{\sigma}\sqrt{x_i}$ ,  $\hat{\sigma} \in \mathbb{R}^+$ .

- Generator associated to multidimensional CIR process :

$$dS_t^i = \hat{k}(\hat{m} - S^i)dt + \hat{\sigma}\sqrt{S_t^i}dW_t^i$$

- Non linearity and solution:

$$f(x, y, z) = ay \sum_{i=1}^d z_i + c(t, x)$$

$$u(t, x) = \cos\left(\sum_{i=1}^d x_i\right)e^{-\alpha(T-t)}.$$

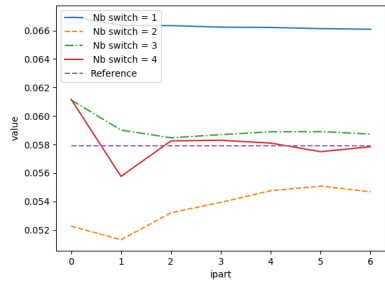
# PDE rewritten as

$$\begin{aligned}(-\partial_t u - \tilde{\mathcal{L}}u)(t, x) &= \tilde{f}(x, u(t, x), Du(t, x), D^2u(t, x)), \\ \tilde{f}(x, u(t, x), Du(t, x), D^2u(t, x)) &= \frac{1}{2}(\bar{\sigma}(x)^2 - \tilde{\sigma}^2)D^2u(t, x) + f(x, u(t, x), Du(t, x)), \\ \tilde{\mathcal{L}}u(t, x) &:= k(m - x)Du(t, x) + \frac{1}{2}\tilde{\sigma}^2 : D^2u(t, x), \\ \tilde{\sigma} &= \bar{\sigma}I_d, \quad \bar{\sigma} \in \mathbb{R}^+\end{aligned}$$

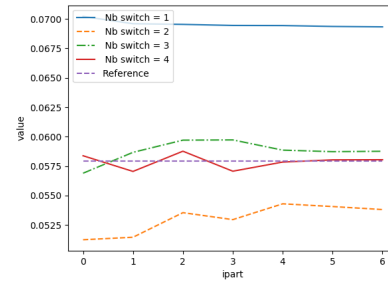
Using Ornstein Uhlenbeck forward process:

$$dS_t^i = \hat{k}(\hat{m} - S^i)dt + \bar{\sigma}dW_t^i.$$

Results :  $N_i^{ipart} = N_i^0 \times 2^{ipart}$

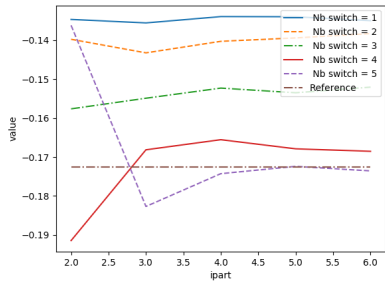


$\lambda = 0.1.$

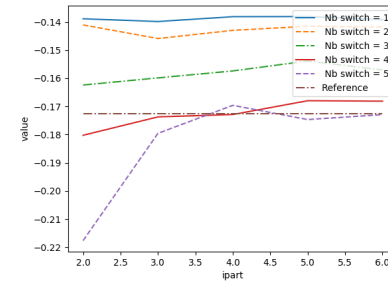


$\lambda = 0.15.$

CIR case dimension 5,  $(N_0^0, N_1^0, N_2^0, N_3^0) = (1000, 50, 25, 12)$



$\lambda = 0.05.$



$\lambda = 0.075.$

CIR case dimension 15,  $(N_0^0, N_1^0, N_2^0, N_3^0, N_4^0) = (1000, 40, 20, 10, 5)$

# Full non linear case (no theoretical result)

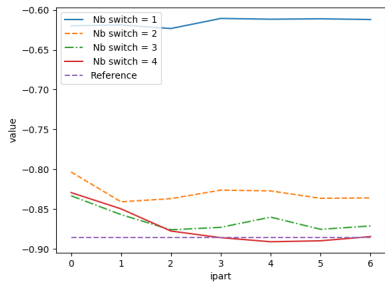
$$\mu = \frac{\mu_0}{d} \mathbf{1}_d,$$
$$\sigma = \frac{\sigma_0}{\sqrt{d}} \mathbf{1}_d,$$

$$f(t, x, y, z, \theta) = e(t, x) + \frac{a}{\sqrt{d}} (-e^{2\alpha(T-t)}) \vee (e^{2\alpha(T-t)} \wedge (y \sum_{i=1}^d \theta_{i,i})),$$

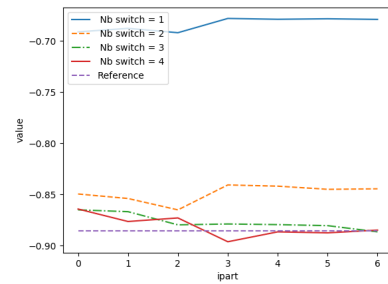
$$u(t, x) = e^{\alpha(T-t)} \cos\left(\sum_{i=1}^d x_i\right).$$

Take:  $\mu_0 = 0.2$ ,  $\sigma_0 = 1$ ,  $\alpha = 0.1$ ,  $x_0 = 0.5 \mathbf{1}_d$ ,  $T = 1$ .

# Figures

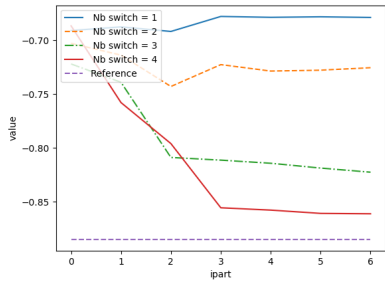


$\lambda = 0.1.$

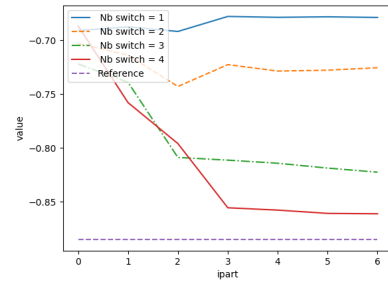


$\lambda = 0.2.$

Full non linear toy example  $a = 0.1, d = 5.$



$\lambda = 0.1.$



$\lambda = 0.2.$

Full non linear toy example  $a = 0.4, d = 5.$



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